









Vision Systems for Robots

Advancing Automation: Innovations in 2D and 3D Imaging for Robotic Vision

Workshop topic

In an increasingly digitalized world, vision systems for stationery and mobile robots open up revolutionary possibilities in automation. From precise object recognition to autonomous navigation to human-robot-interaction – these technologies are a key driver for innovative robotics applications in industry.

The workshop is dedicated to the current developments, challenges, and application areas of vision systems. Experts and practitioners will exchange their knowledge of modern image processing technologies, machine learning, and their integration into robot platforms. Topics discussed include the optimization of recognition algorithms, sensor fusion, and their impact on the productivity and flexibility of industrial processes.

The goal of the workshop is to connect science, industry, and practitioners to jointly shape the future of robotics with vision systems. Participants will gain valuable insights into the state of the art and learn best practices for implementing these technologies in various application areas.

Date / Location

Date: 9. Sept. 2025

Duration: 10.15 a.m. – 6 p.m.

Location: Fachhochschule Graubünden, Pulvermühlestrasse 57, 7000 Chur

Target audience

This workshop will be a forum for participants from industry and research to share their experiences and discuss challenges and perspectives of current and future applications.

Cost

This workshop is free of charge

Registration compulsory

Registration link, Registration Deadline: 29. Aug. 2025

Language

English preferred

Organized by the University of Applied Sciences of the Grisons, University of Applied Sciences Eastern Switzerland, Swissphotonics and Swissmem Photonics Booster











| Time | Presentation & Topic |
|---------|--|
| 10:15 h | Registration, Welcome Coffee |
| 10:45 h | Welcome to the University of Applied Sciences of the Grisons Gian-Paolo Curcio, FH Graubünden |
| 11:00 h | Introduction to the Workshop Christoph S. Harder & Christian Erik Thöny |
| 11:10 h | Vision Systems for Robots, Organizational remarks, Lab tour Udo Birk, FH Graubünden |
| 11:30 h | Lab Tour FHGR |
| 12:30 h | Lunch, 1 h |
| 13:30 h | Uncrewed Surface Vehicle for Underwater Monitoring of Aquatic Plants Manuel Schlegel, FH Graubünden |
| 13:45 h | Advanced Camera Technologies Shaping the Future of Robotic Vision Peter Schwider, Photonfocus |
| 14:00 h | Advanced Visual Perception for Articulated Robotic Systems and Environmental Mapping Katrin Lohan, FH OST |
| 14:15 h | How the Next Generation TOF Imager enhances Robotic Vision Cengiz Küpçü, Espros |
| 14:30 h | Panel Discussion / Q&A Session 1 with Manuel Schlegel, Peter Schwider, Katrin Lohan & Cengiz Küpçü |
| 14:50 h | Coffee Break, 30 min |
| 15:20 h | Laser-Assisted Robot-Guided Cartilage Regeneration Michael Sommerhalder, University of Basel |
| 15:35 h | Laser Illuminators for Robotics Julien Boucart, Coherent |
| 15:50 h | Assistive Robots for Healthcare Roland Siegwart, ETH Zürich |
| 16:05 h | Vision for Collaborative Robots Ambra Vandone, SUPSI |
| 16:20 h | Panel Discussion / Q&A Session 2 with Michael Sommerhalder, Julien Boucart, Roland Siegwart, Ambra Vandone |
| 16:40 h | Opportunities for innovative forces: Engineers and Professors Christoph S. Harder, Swissphotonics |
| 16:50 h | Call for Radical innovation Christian Erik Thöny, Swissmem Photonics / Photonics Booster |
| 17:00 h | Networking Apéro |